

## System Outline

Multiplex Communication System (CAN) uses a serial communication protocol and communicates with a differential voltage. In this network system, TERMINALS CANH and CANL are used for communication between the ECUs and sensors, and excellent data communication speed and communication error detecting facility are provided. This system is working for the following system:

- \* Cruise Control (1ZZ-FE)
- \* Engine Control (1ZZ-FE)
- \* Multi-Mode Manual Transmission
- \* VSC

## ○ : Parts Location

Code	See Page	Code	See Page	Code	See Page
E5	45 (LHD)	M1	46 (LHD)	S16	47 (LHD)
	55 (RHD)		56 (RHD)		57 (RHD)
J14	45 (LHD)	S5	41 (*1)	Y1	47 (LHD)
	55 (RHD)		43 (*2)		57 (RHD)
J15	45 (LHD)		51 (*3)		
	55 (RHD)		53 (*4)		

## □ : Connector Joining Wire Harness and Wire Harness

Code	See Page	Joining Wire Harness and Wire Harness (Connector Location)
IA2	64 (LHD)	Engine Room Main Wire and Instrument Panel Wire (Behind the Combination Meter)
	74 (RHD)	Engine Room Main Wire and Instrument Panel Wire (Left Side of the Instrument Panel)

## ▽ : Ground Points

Code	See Page	Ground Points Location
IK	64 (LHD)	Behind the Combination Meter
	74 (RHD)	

\* 1 : LHD 1ZZ-FE, 3ZZ-FE    \* 2 : LHD 1CD-FTV    \* 3 : RHD 1ZZ-FE, 3ZZ-FE    \* 4 : RHD 1CD-FTV    \* 5 : 1ZZ-FE, 3ZZ-FE    \* 6 : 1CD-FTV